Aarambh Sinha

* Discussed with the group on the best strategy for control. As a group, decided to change to using analogue sensors as it will help programming for PID easier to manage with, better accurate results, compared to digital inputs.
* Worked on stripboard implementation with Marlon and Abdullah. Redesigned circuit from outputting digital data to analogue as decided by group.
* Redesigned PCB schematic to now output analogue data.
* Redesigned and finished PCB design ready to be printed for Monday 4th March.
* Improved signal strength of sensors by adding a pair of decoupling capacitors. Ensures the sensor circuit still works consistently under varying loads of the motor drive board.